

INFORMATION TECHNOLOGY FOR DISTRIBUTED ENGINEERING SYSTEMS

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- Distributed environments and applications
- Exchange of data
 - XML
- Remote objects
 - RMI
 - CORBA
- Object structures and algorithms in engineering
 - Dependencies of objects
 - Sequence of modification
- Conclusion

Object oriented method

- An application consists of **structured sets of objects**
- Each object consists of **methods** and **attributes**
 - The methods describe the behaviour of an object
 - The attributes contain the data which is stored in an object

Distributed environments

- Exchange of **data**
 - Remote method invocation
 - Exchange of files
- Using remote **functionality**
 - Remote method invocation

Exchange of Data

Extensible Markup Language (XML)

- XML is a document processing standard proposed by the World Wide Web Consortium (W3C)
- XML is a meta-language that allows you to create your own document markups
- XML documents are similar to HTML documents (in fact, HTML can be defined in XML)

Overview of an XML document

- XML Document (required)
- Document Type Definition (DTD) (optional)
- Stylesheet (XSL, XSLT) (optional)

Example of a simple XML document

```
▶ <?xml version="1.0" standalone="no"?>
  <!DOCTYPE objects SYSTEM "objects.dtd">
  <!-- this is a comment -->
  <objects>
    <point id="x1" x="1.0" y="1.0"/>
    <point id="x2" x="3.0" y="1.5"/>
    <point id="x3" x="2.0" y="2.0"/>
    <triangle id="x4">
      <p1>x1</p1>
      <p2>x2</p2>
      <p3>x3</p3>
    </triangle>
  </objects>
```

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    <p2>x2</p2>
    <p3>x3</p3>
  </triangle>
</objects>
```

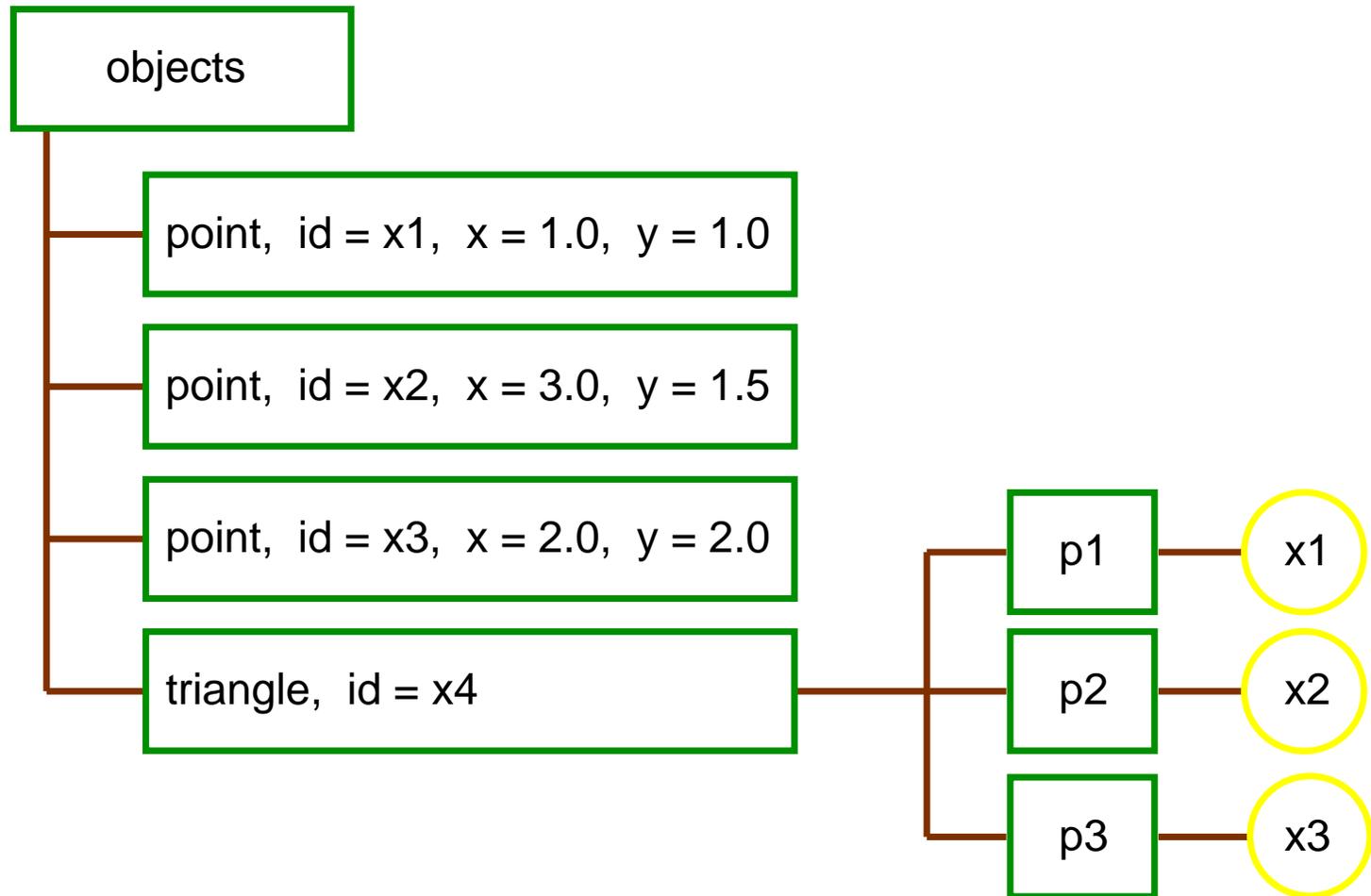
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    <p1>x1</p1>
    <p2>x2</p2>
    <p3>x3</p3>
  </triangle>
</objects>
```

Hierarchy :



Document Type Definition (DTD) : 'objects.dtd'

```
<!ELEMENT objects (triangle*,point*)>
```

```
<!ELEMENT point EMPTY>
```

```
<!ATTLIST point id ID #REQUIRED  
                x CDATA #REQUIRED  
                y CDATA #REQUIRED>
```

```
<!ELEMENT triangle (p1,p2,p3)>
```

```
<!ATTLIST triangle id ID #REQUIRED>
```

```
<!ELEMENT p1 (#PCDATA)>
```

```
<!ELEMENT p2 (#PCDATA)>
```

```
<!ELEMENT p3 (#PCDATA)>
```

Extensible Stylesheet Language (XSL)

Extensible Stylesheet Language Transformations (XSLT)

- XSL is used to describe how an XML source document is transformed into another document
- XSL documents are themselves XML documents

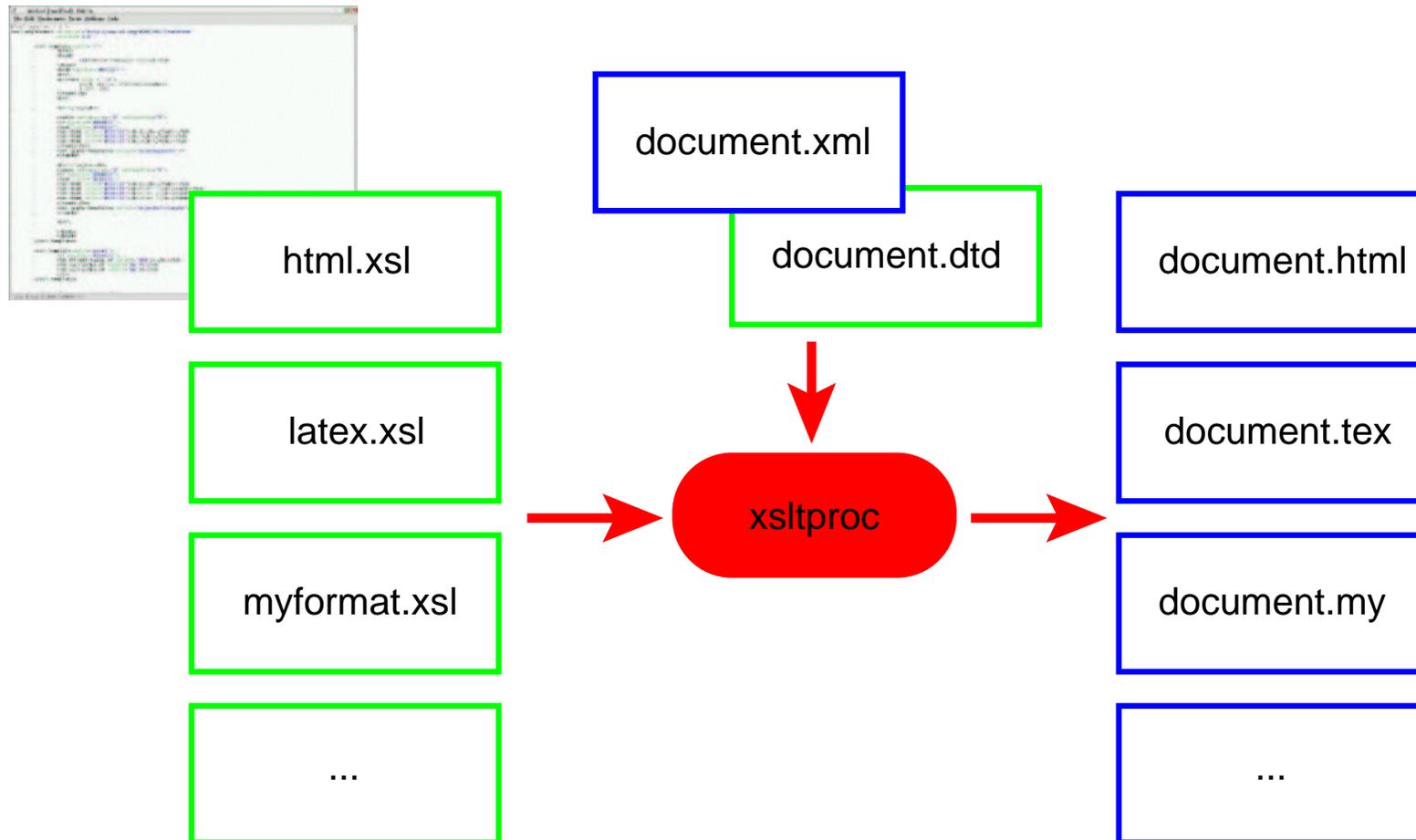
```

html.xsl [modified] - KWrite
File Edit Bookmarks Tools Settings Help
k?xml version='1.0'?>
<xsl:stylesheet xmlns:xsl="http://www.w3.org/1999/XSL/Transform"
  version='1.0'>
  <xsl:template match="/">
    <html>
    <head>
      <title>Stellenbosch 2002</title>
    </head>
    <body bgcolor="#FFFFFF">
    <hr/>
    <p><font size = "+2">
      South Africa, Stellenbosch<br/>
      4 Oct. 2002
    </font></p>
    <hr/>
    <h1>Points</h1>
    <table cellspacing="2" cellpadding="5">
    <tr bgcolor="#0000FF">
    <font color="#FFFFFF">
    <td><font color="#FFFFFF"><b>ID</b></font></td>
    <td><font color="#FFFFFF"><b>x</b></font></td>
    <td><font color="#FFFFFF"><b>y</b></font></td>
    </font></tr>
    <xsl:apply-templates select="objects/point"/>
    </table>
    <h1>Triangles</h1>
    <table cellspacing="2" cellpadding="5">
    <tr bgcolor="#0000FF">
    <font color="#FFFFFF">
    <td><font color="#FFFFFF"><b>ID</b></font></td>
    <td><font color="#FFFFFF"><b>Point 1</b></font></td>
    <td><font color="#FFFFFF"><b>Point 2</b></font></td>
    <td><font color="#FFFFFF"><b>Point 3</b></font></td>
    </font></tr>
    <xsl:apply-templates select="objects/triangle"/>
    </table>
    <hr/>
    </body>
    </html>
  </xsl:template>
  <xsl:template match="point">
    <tr bgcolor="#CCCCCC">
    <td><b><xsl:value-of select="@id"/></b></td>
    <td><xsl:value-of select="@x"/></td>
    <td><xsl:value-of select="@y"/></td>
    </tr>
  </xsl:template>

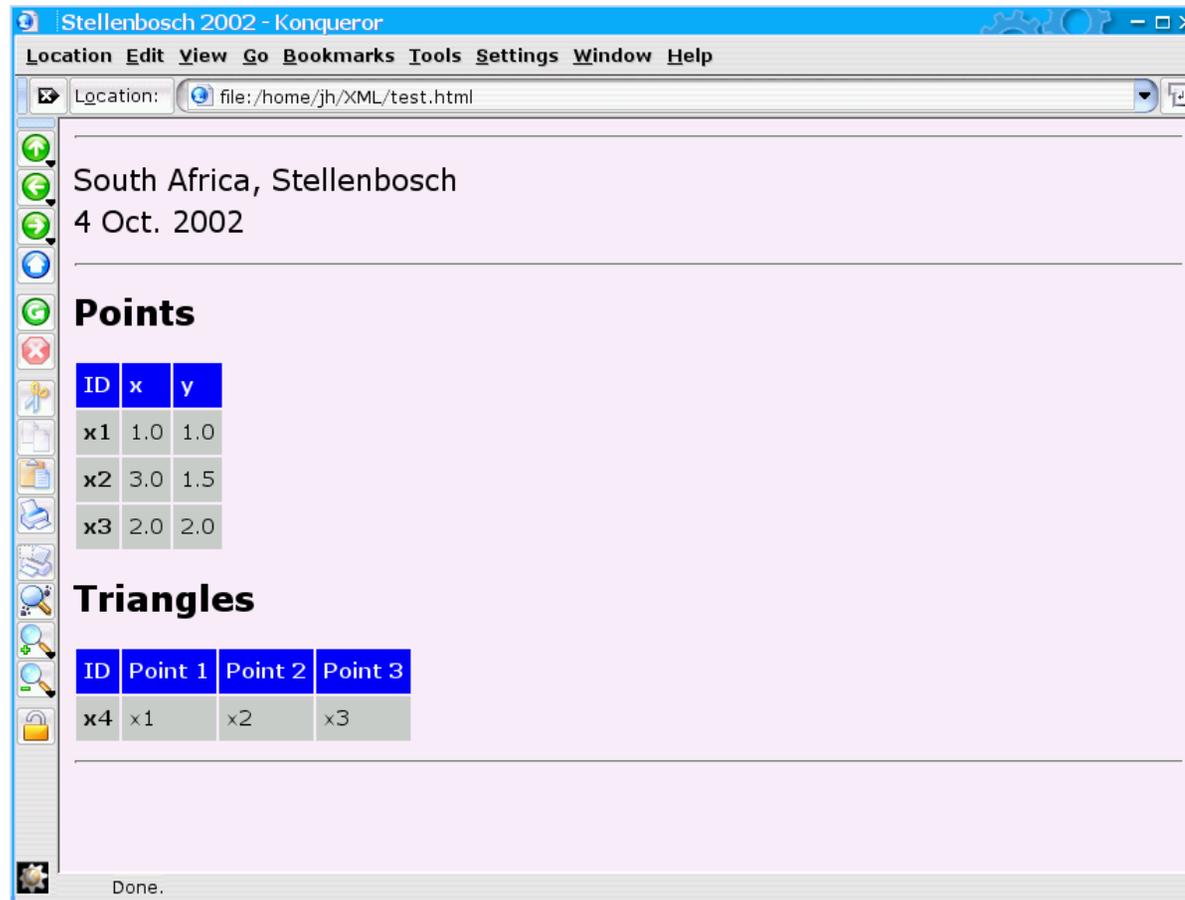
```

Line: 1 Col: 0 INS NORM *

Extensible Stylesheet Language Transformations (XSLT)



Extensible Stylesheet Language (XSL)



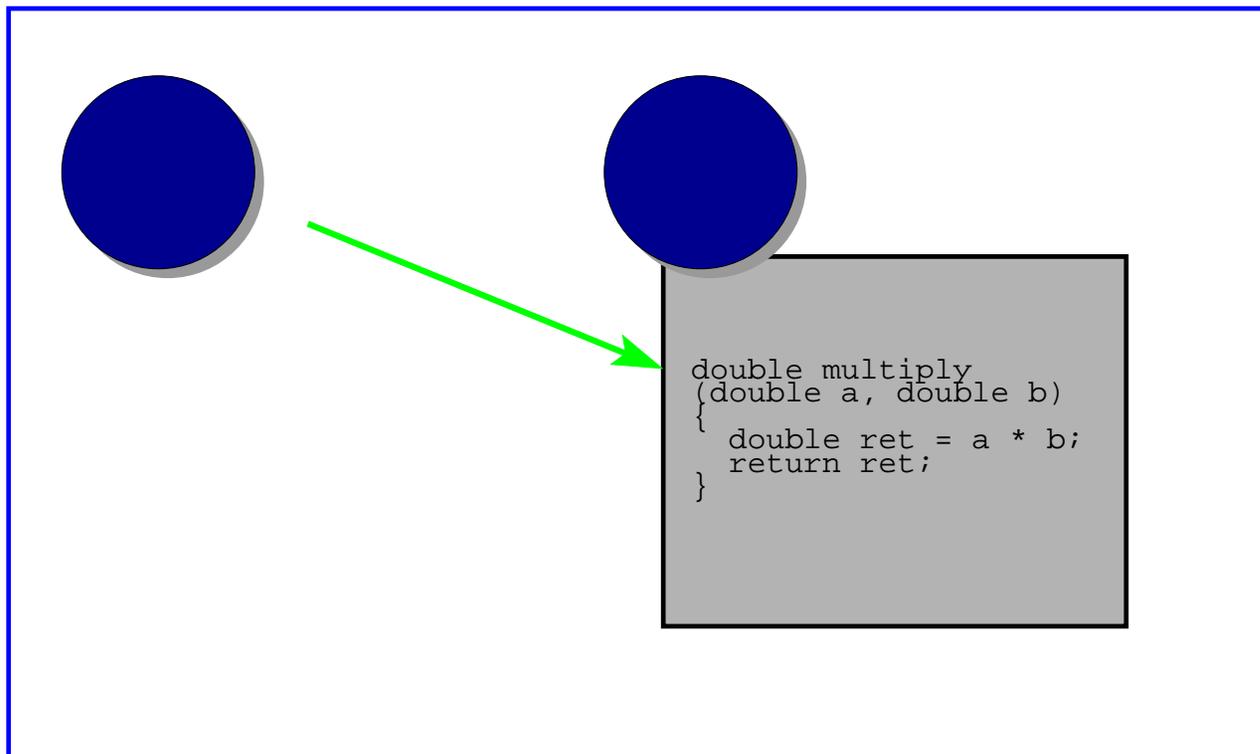
Advantages of XML

- structured data
- standardized description of structure
- tools available
(parser, xslt processor, xml validator ...)

Disadvantages of XML

- File size
- Increased processing time

Using remote functionality



Client/server model



Using remote functionality

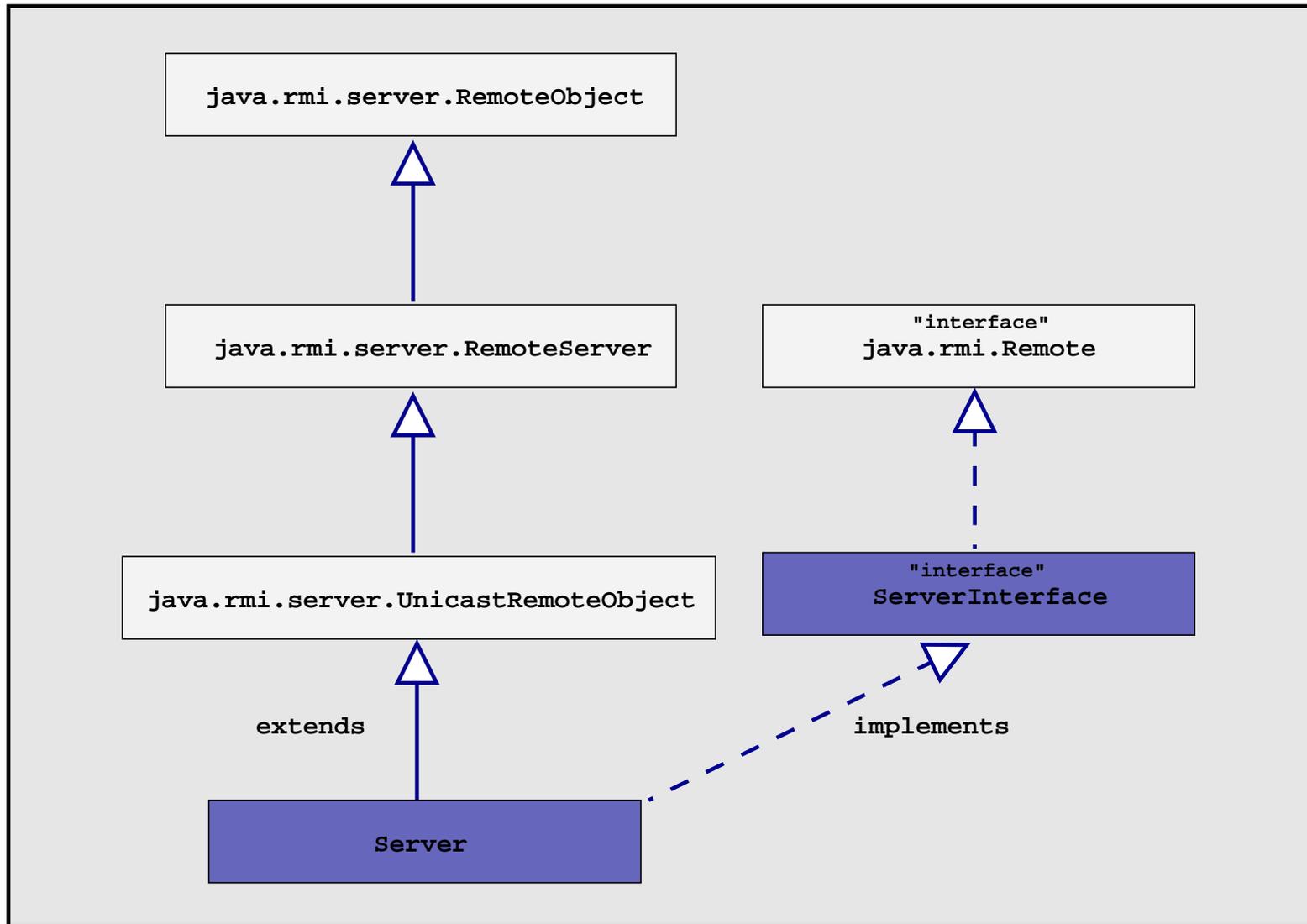
JAVA Remote method invocation (RMI)

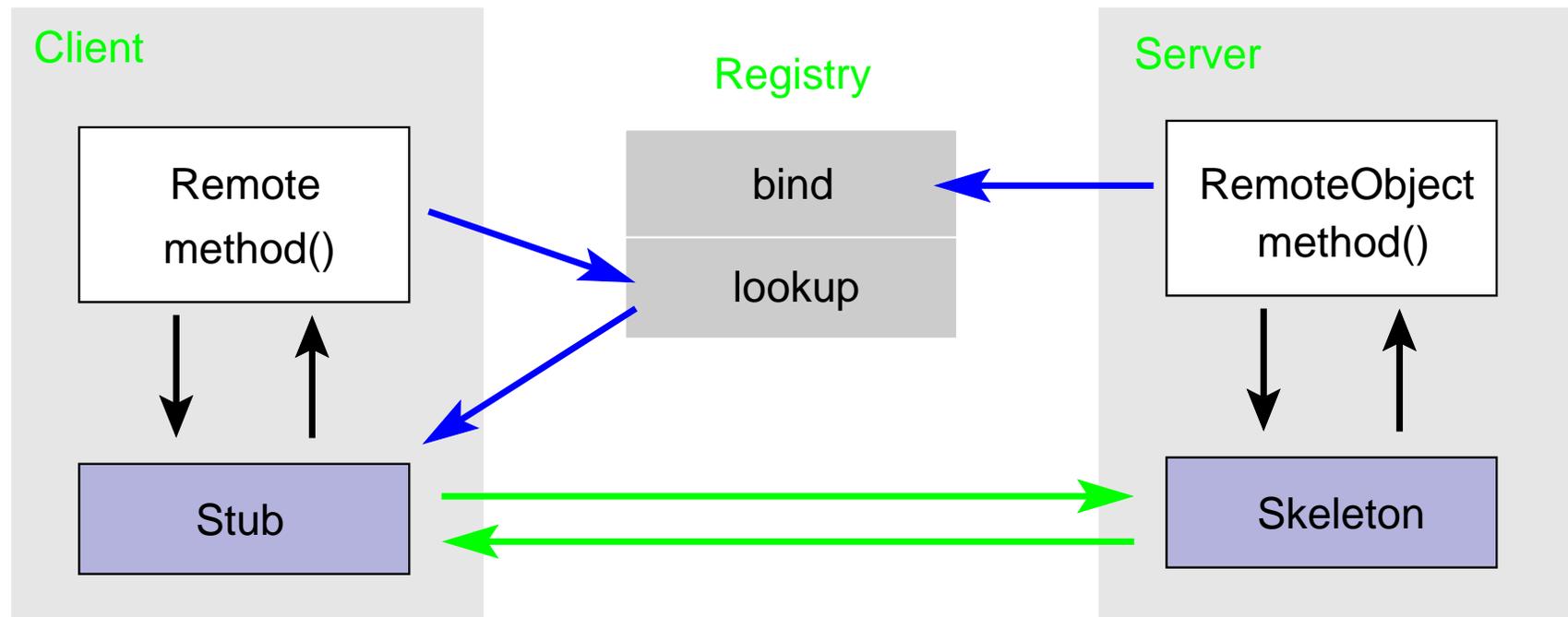
- Available since JAVA 1.1
- RMI is a mechanism that enables an object on one Java virtual machine to invoke methods on an object in another Java virtual machine

JAVA Remote method invocation (RMI)

1. Define a JAVA interface which inherits `java.rmi.Remote`
3. Define a server class which inherits `java.rmi.server.UnicastRemoteObject` and which implements your interface
4. Generate stubs/skeletons using `rmic`
5. Bind object to JAVA registry

Class hierarchy for remote objects





Advantages of JAVA RMI

- Easy to use
- No additional interface description language

Disadvantages of JAVA RMI

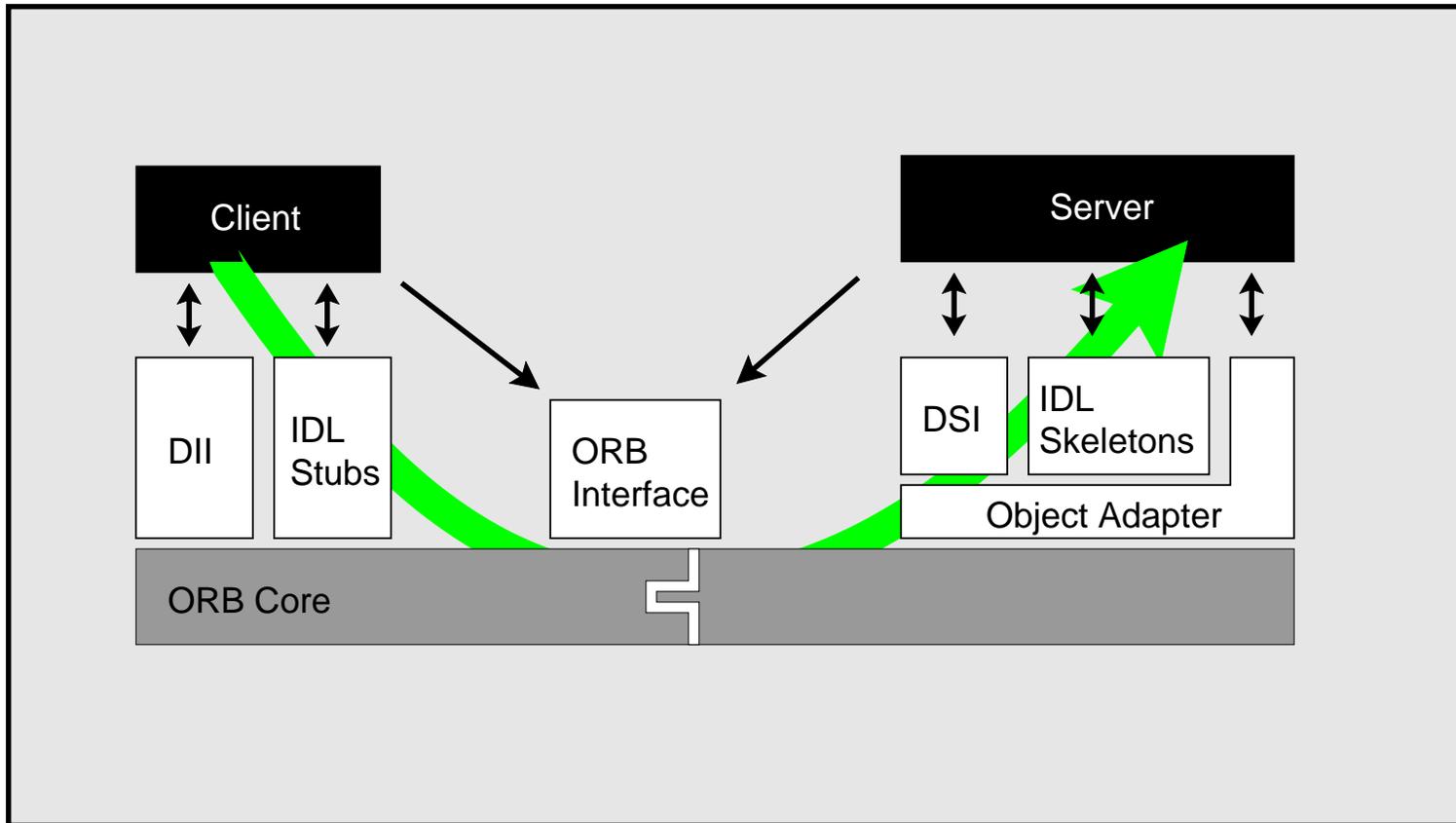
- Limited to JAVA platform

Common Object Request Broker Architecture (**CORBA**)

- Specified by the Object Management Group (OMG)
- Platform for distributed object oriented applications in heterogeneous environments
- Language bindings for C++, JAVA, Smalltalk ...
- Commercial and free implementations

Parts of CORBA

- Interface Definition Language (IDL)
- ORB Core
- ORB Interface
- Static interfaces (stubs, skeletons)
- Dynamic Interfaces (Dynamic Skeleton Interface, Dynamic Invocation Interface)
- Object Adapters (Basic Object Adapter, Portable Object Adapter)
- Inter-ORB protocols



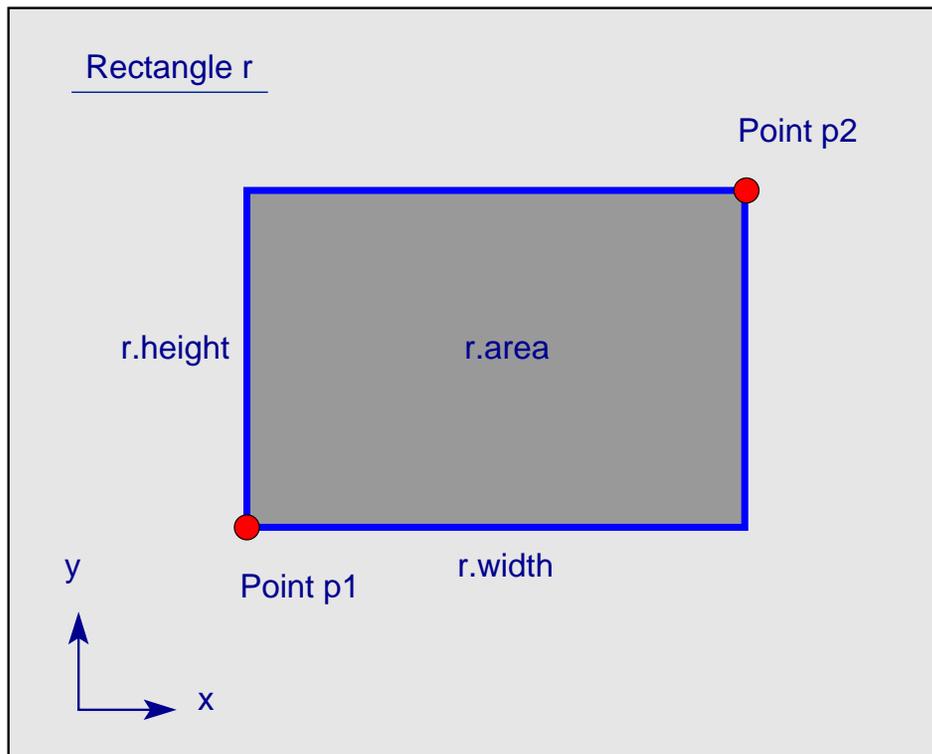
Advantages of CORBA

- Platform independent
- Language bindings for several languages
- Standardized services (notification, life cycle, trading ...)

Disadvantages of CORBA

- Increased overhead
- Performance (?)

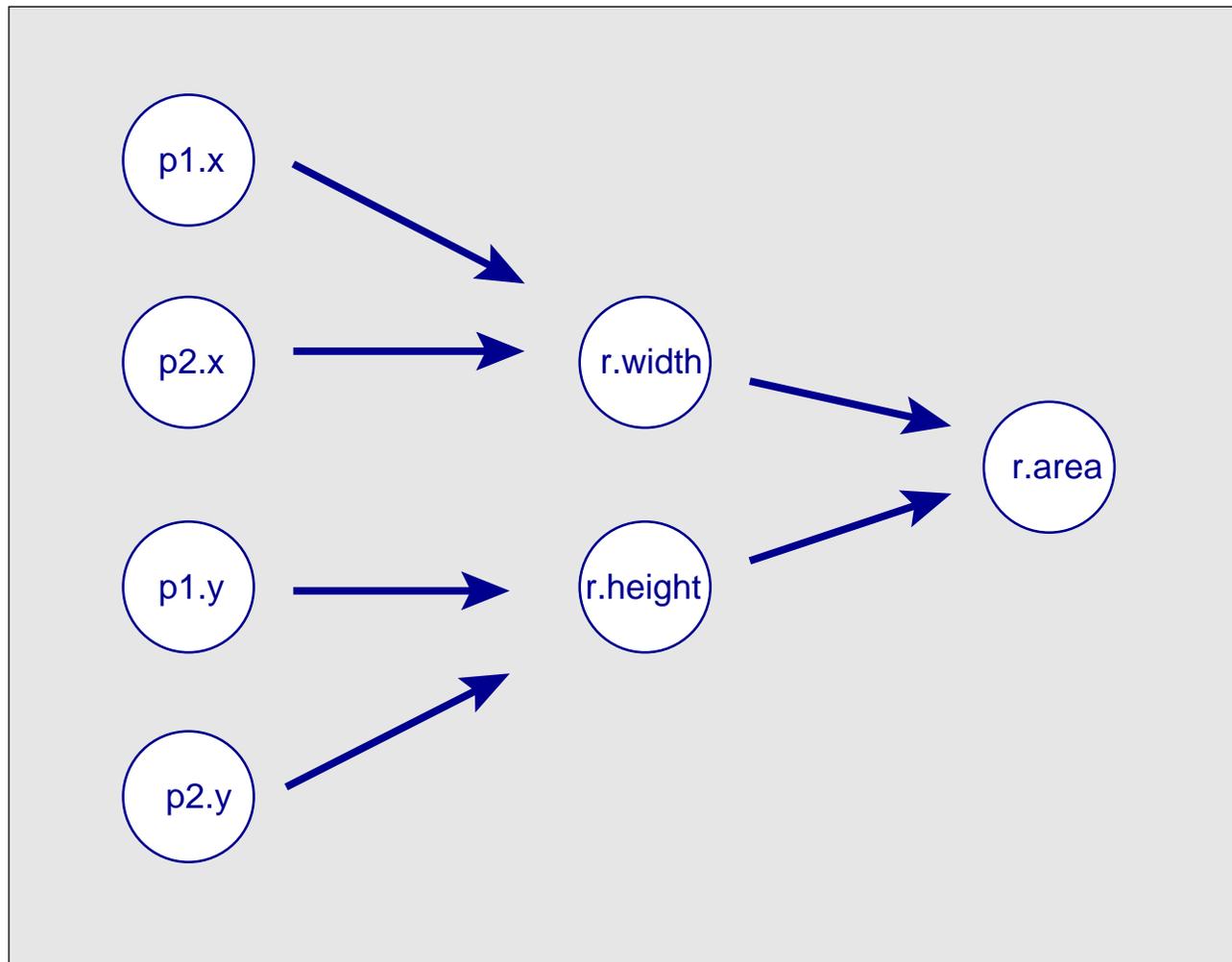
Dependencies of objects



$$r.area = r.height \cdot r.width$$

$$r.height = p2.y - p1.y$$

$$r.width = p2.x - p1.x$$



Object structures and algorithms in engineering

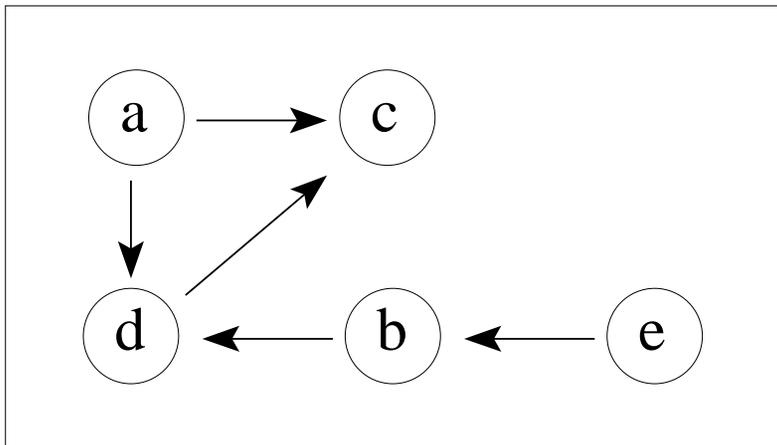
- High **complexity** of objects
- **Relations** to other objects are manifold
- Complex algorithms with **high computational effort**

This leads to :

- **Delayed** updates
- Correct **sequence of modification** of attributes has to be determined

⇒ **Graph theory**

$$B := \{ (a, b) \in A \times A \mid a \text{ binds } b \}$$

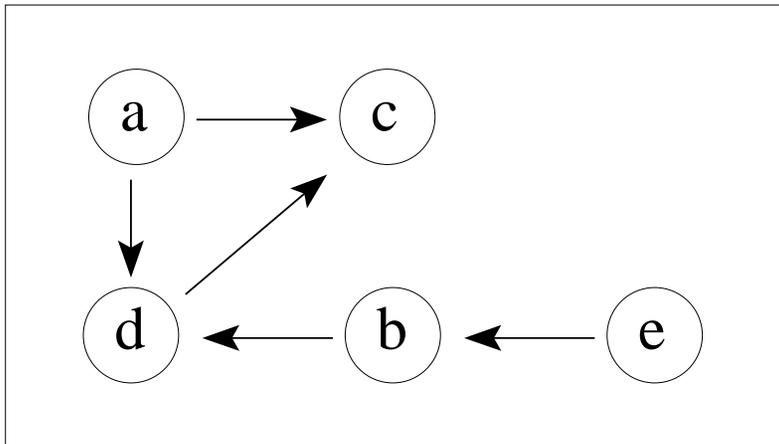


$$B = \{ (a, d), (a, c), (d, c), (b, d), (e, b) \}$$

$$B = \begin{bmatrix} \circ & \circ & \bullet & \bullet & \circ \\ \circ & \circ & \circ & \bullet & \circ \\ \circ & \circ & \circ & \circ & \circ \\ \circ & \circ & \bullet & \circ & \circ \\ \circ & \bullet & \circ & \circ & \circ \end{bmatrix} \begin{matrix} a \\ b \\ c \\ d \\ e \end{matrix}$$

$a \quad b \quad c \quad d \quad e$

$$H := \{ (a, b) \in A \times A \mid b \text{ depends on } a \}$$



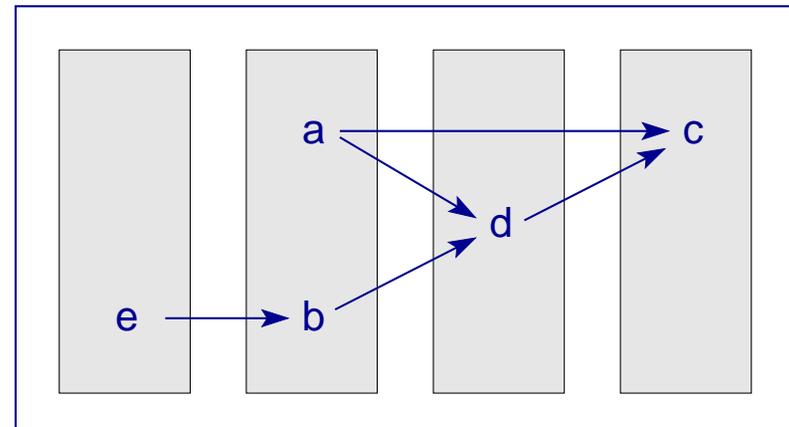
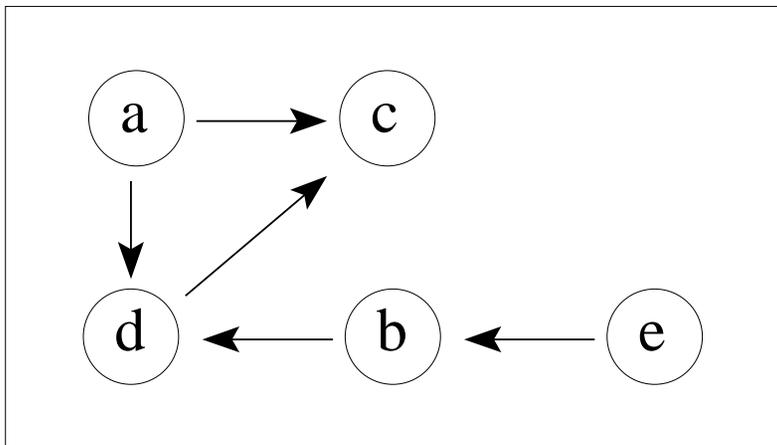
$$H = B \cup B^2 \cup \dots \cup B^{n-1}$$

$$H = \begin{bmatrix} \circ & \circ & \bullet & \bullet & \circ \\ \circ & \circ & \bullet & \bullet & \circ \\ \circ & \circ & \circ & \circ & \circ \\ \circ & \circ & \bullet & \circ & \circ \\ \circ & \bullet & \bullet & \bullet & \circ \end{bmatrix} \begin{matrix} a \\ b \\ c \\ d \\ e \end{matrix}$$

a *b* *c* *d* *e*

Sequence of modification

Topological sorting



Attribute c has to be updated.

Correct sequence of modification : $\langle e, a, b, d, c \rangle$

System

1. Elements

E : Set of elements

2. Properties

F : Set of properties

3. Algorithms

$(f_1, \dots, f_m) \longrightarrow \boxed{A} \longrightarrow (h_1, \dots, h_n)$

A : Set of algorithms

4. Complete binding relation

$B := (A, F, R_e, R_a)$

$R_e \subseteq F \times A$ Input parameters, algorithms

$R_a \subseteq A \times F$ Algorithms, output parameters

5. System

$S := (E, A, F; B)$

Update of a system

Choosing properties which have to be updated :

$$Z := \{a \in F \mid a \text{ is chosen for an update}\}$$

Domain of properties :

$$D_F := \{a \in F \mid a \text{ has to be updated}\}$$

Domain of algorithms :

$$D_A := \{A \in A \mid \text{Algorithm } A \text{ must be invoked for updating} \\ \text{an element in } D_F \}$$

Domain of update :

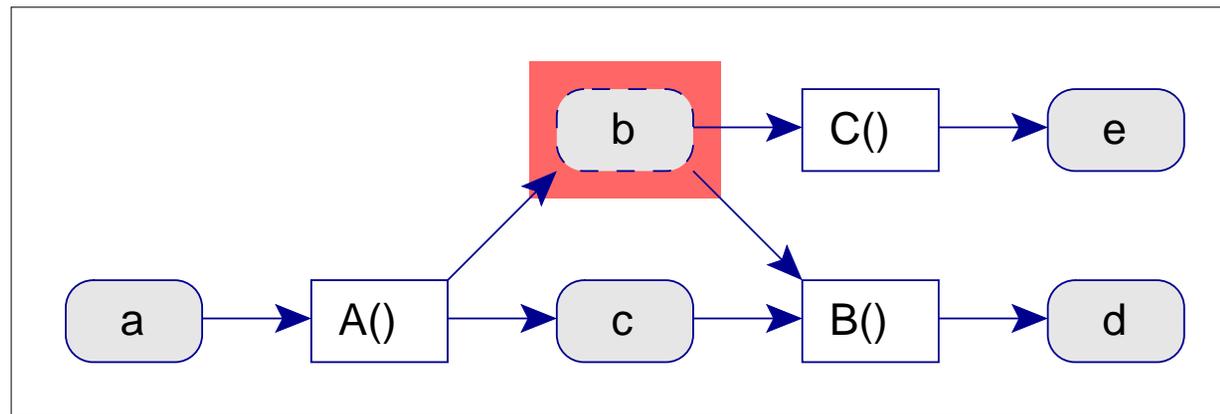
$$D = D_A \cup D_F$$

Reduced binding relation

$$\bar{B} = \Gamma^T B \Gamma$$

$$\bar{B} := \{(a, b) \in D \times D \mid (a, b) \in B\}$$

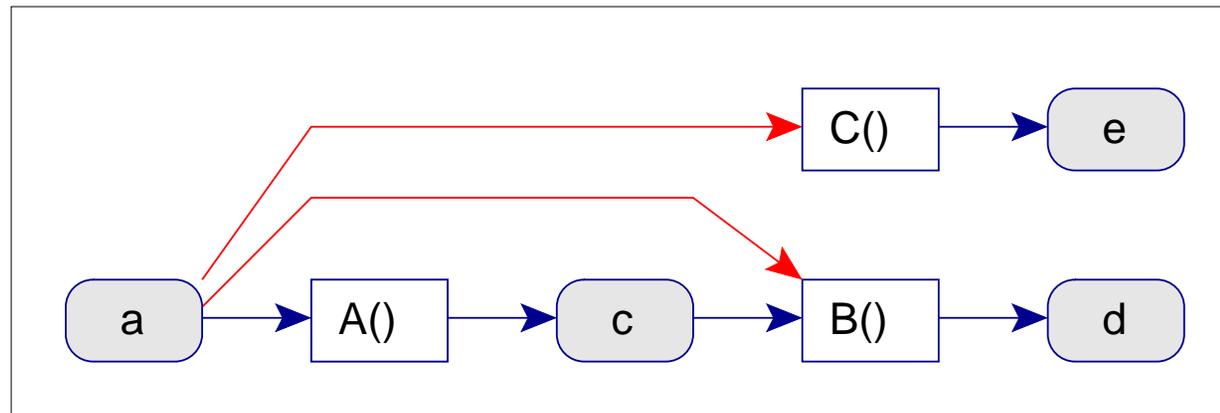
Removing virtual properties



$$\bar{B} = \{(a, A), (A, b), (A, c), (b, C), (b, B), (c, B), (C, e), (B, d)\}$$

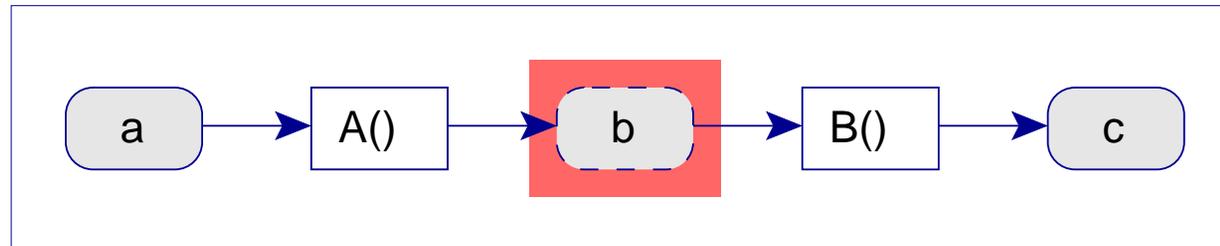
$$D = \{a, A, b, c, C, B, e, d\}$$

Removing virtual properties



$$\begin{aligned}
 \bar{B}_v &= \bar{B} \setminus \{(A, b), (b, C), (c, B), (b, B)\} \cup \{(a, C), (a, B)\} \\
 &= \{(a, A), (a, C), (a, B), (A, c), (c, B), (C, e), (B, d)\} \\
 D_v &= \{a, A, c, C, B, e, d\}
 \end{aligned}$$

Removing methods without successors



$$\bar{B} = \{(a, A), (A, b), (b, B), (B, c)\}$$

$$D = \{a, A, b, B, c\}$$

Removing methods without successors



$$\bar{B}_v = \{(a, A), (a, B), (B, c)\}$$

$$D_v = \{a, A, B, c\}$$

Removing methods without successors



$$\bar{B}_{v,m} = \{(a, B), (B, c)\}$$

$$D_{v,m} = \{a, B, c\}$$

Sequence of modification

Calculation of \bar{B}_A

$$\bar{B}_A = \Gamma_A^T \bar{B}_{v,m}^2 \Gamma_A$$

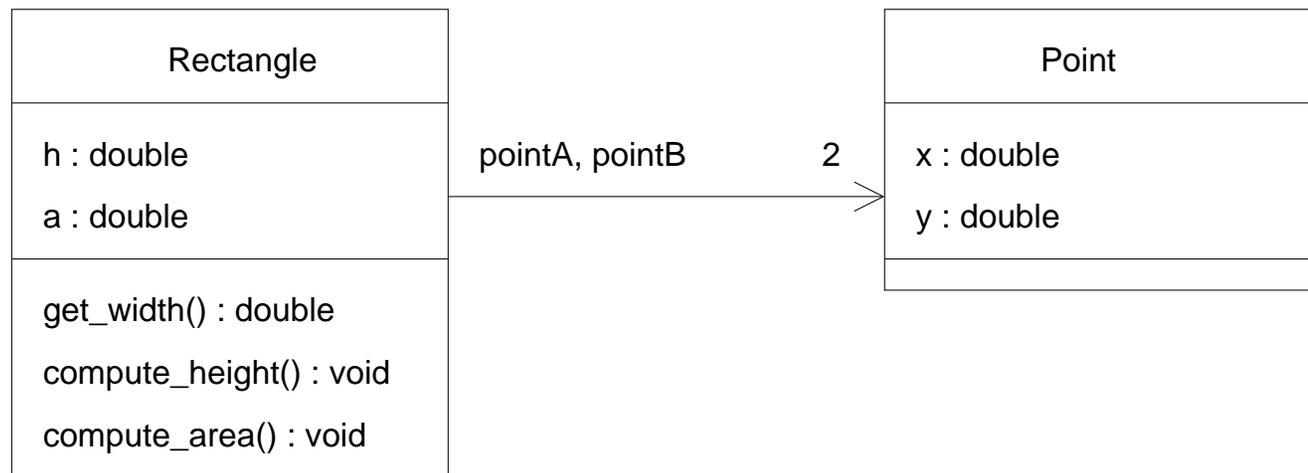
Topological sorting

$$\bar{B}_A \rightarrow a$$

Invoking methods

$$a = \langle B, D, A, \dots \rangle$$

Example



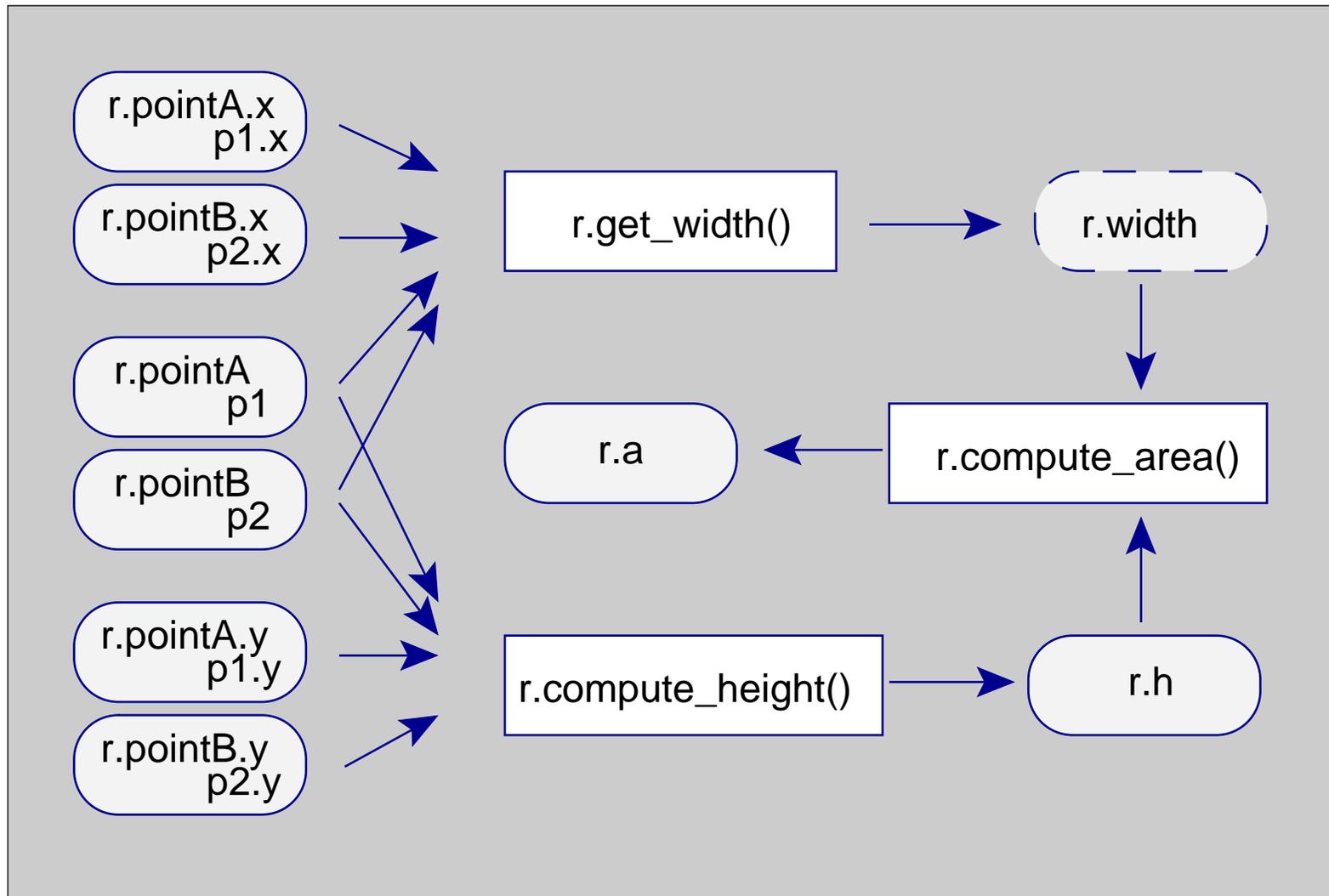
Objects $E = \{ r, p1, p2 \}$

Properties $F = \{ p1.x, p1.y, p2.x, p2.y, r.pointA, r.pointB, r.width, r.h, r.a \}$

Algorithms $A = \{ r.get_width(), r.compute_height(), r.compute_area() \}$

$(r.pointA.x, r.pointB.x)$	\longrightarrow	$r.get_width()$	\longrightarrow	$(r.width)$
$(r.pointA.y, r.pointB.y)$	\longrightarrow	$r.compute_height()$	\longrightarrow	$(r.h)$
$(r.h, r.width)$	\longrightarrow	$r.compute_area()$	\longrightarrow	$(r.a)$

	<i>p1.x</i>	<i>p1.y</i>	<i>p2.x</i>	<i>p2.y</i>	<i>r.pointA</i>	<i>r.pointB</i>	<i>r.h</i>	<i>r.a</i>	<i>r.width</i>	<i>r.get_width()</i>	<i>r.compute_area()</i>	<i>r.compute_height()</i>
<i>p1.x</i>	●											
<i>p1.y</i>		●										
<i>p2.x</i>			●									
<i>p2.y</i>				●								
<i>r.pointA</i>					●							
<i>r.pointB</i>						●						
<i>r.h</i>							●					
<i>r.a</i>								●				
<i>r.width</i>									●			
<i>r.get_width()</i>										●		
<i>r.compute_area()</i>											●	
<i>r.compute_height()</i>												●



$$Z = \{r.a\}$$

$$D_F = \{r.a, r.breite, r.h, r.punktA, r.punktB, p1.x, p1.y, p2.x, p2.y\}$$

$$D_A = \{r.berechne_flaeche(), r.breite(), r.berechne_hoehe()\}$$

$$D = D_F \cup D_A$$

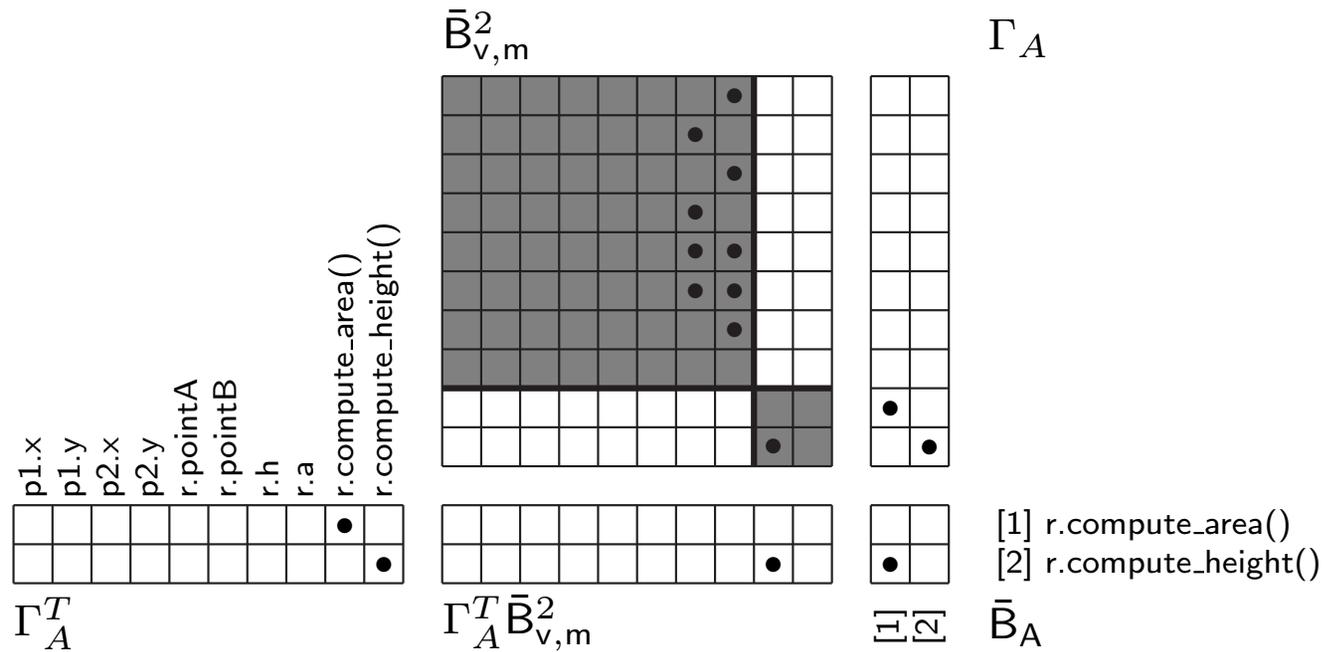
$$= \{r.a, r.breite, r.h, r.berechne_flaeche(), r.breite(), r.berechne_hoehe(), r.punktA, r.punktB, p1.x, p1.y, p2.x, p2.y\}$$

	p1.x	p1.y	p2.x	p2.y	r.pointA	r.pointB	r.h	r.a	r.width	r.get_width()	r.compute_area()	r.compute_height()
p1.x										⬆	×	
p1.y												•
p2.x										⬆	×	
p2.y												•
r.pointA										⬆	×	•
r.pointB										⬆	×	•
r.h											•	
r.a												
r.width	-	-	-	-	-	-	-	-	+	+	⬆	-
r.get_width()	-	-	-	-	-	-	-	-	+	+	-	-
r.compute_area()							•					
r.compute_height()						•						

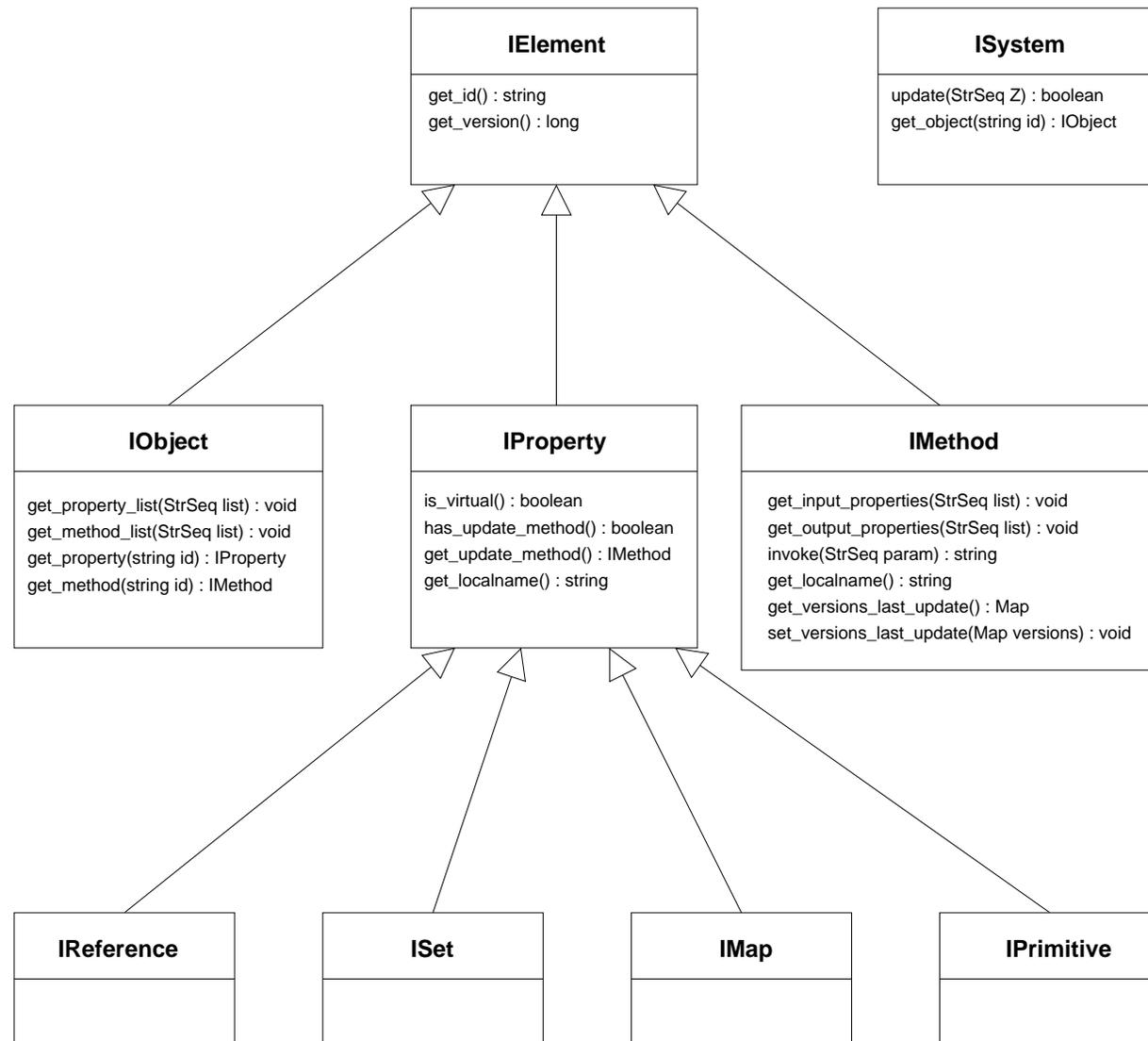
	p1.x	p1.y	p2.x	p2.y	r.pointA	r.pointB	r.h	r.a	r.compute_area()	r.compute_height()	
p1.x										•	
p1.y											•
p2.x										•	
p2.y											•
r.pointA										•	•
r.pointB										•	•
r.h										•	
r.a											
r.compute_area()									•		
r.compute_height()							•				

$\bar{B}_{v,m}$

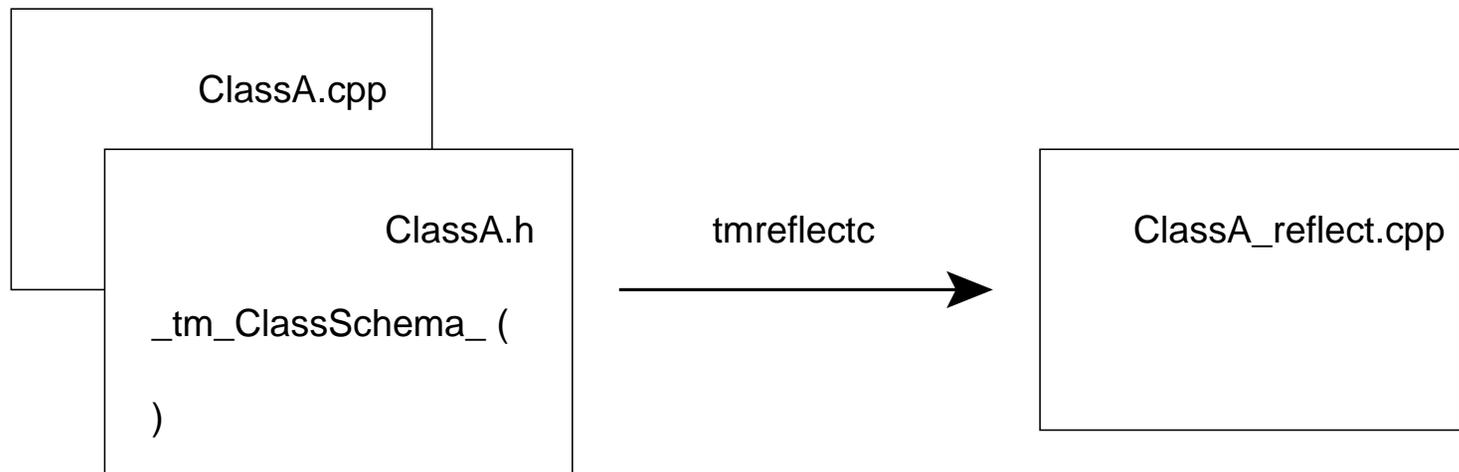
$$\bar{B}_A = \Gamma_A^T \bar{B}_{v,m}^2 \Gamma_A \quad (1)$$



Topological sorting : $\bar{B}_A \rightarrow \langle r.compute_height(), r.compute_area() \rangle$



Metacompiler



```
class Point : public tm_core::tmObject
{
public:

    _tm_ClassSchema_
    ( <class name="Point">

        <superclass>tm_core::tmObject</superclass>

        <primitive name="X">
            <datatype>double</datatype>
            <read>get_x</read>
            <write>set_x</write>
            <activate>activate_x</activate>
            <info>"Coordinate x."</info>
        </primitive>

        <primitive name="Y">
            <datatype>double</datatype>
            <read>get_y</read>
            <write>set_y</write>
            <activate>activate_y</activate>
            <info>"Coordinate y."</info>
        </primitive>

        </class> );

    Point(double x, double y, tm_core::tmRepository* repo = 0);
```

```
Point(tm_core::tmRepository* repo = 0);
double get_x() const { return _x; }
bool set_x(double value);
double get_y() const { return _y; }
bool set_y(double value);
void set_xy(double x, double y);

protected:

/* -- this is needed for persistence ----- */
TM_OBJECT
Point(const QString& id, tm_core::tmRepositoryP* repo = 0)
    : tm_core::tmObject(id,repo) {
    init();
}
void activate_x(double x) { _x = x; }
void activate_y(double y) { _y = y; }
/* ----- */

private:

void init();
double _x, _y;

};
```

```
class Rectangle : public tm_core::tmObject
{
public:

    _tm_ClassSchema_
    ( <class name="Rectangle">
      <superclass>tm_core::tmObject</superclass>

      <primitive name="Width" virtual="true">
        <datatype>double</datatype>
        <read>get_width</read>
        <info>"Width of rectangle."</info>
      </primitive>

      <primitive name="Height">
        <datatype>double</datatype>
        <read>get_height</read>
        <activate>activate_height</activate>
        <info>"Height of rectangle."</info>
      </primitive>

      <primitive name="Area">
        <datatype>double</datatype>
        <read>get_area</read>
        <activate>activate_area</activate>
        <info>"Area of rectangle."</info>
      </primitive>
    )
};
```

```
<reference name="point_A">
  <datatype>Point</datatype>
  <read>get_point_A</read>
  <activate>activate_Point_A</activate>
</reference>
```

```
<reference name="point_B">
  <datatype>Point</datatype>
  <read>get_point_B</read>
  <activate>activate_Point_B</activate>
</reference>
```

```
<method name="compute_height">
  <returntype>void</returntype>
  <input>point_A.Y</input>
  <input>point_B.Y</input>
  <output>Height</output>
</method>
```

```
<method name="compute_area">
  <returntype>void</returntype>
  <input>Height</input>
  <input>Width</input>
  <output>Area</output>
</method>
```

```
<method name="get_width">
  <returntype>double</returntype>
```

```
        <input>point_A.X</input>
        <input>point_B.X</input>
        <output>Width</output>
    </method>

</class> );

Rectangle(Point* p1, Point* p2, tm_core::tmRepository* repo = 0);
double  get_width()      { return _point_B->get_x() - _point_A->get_x(); }
double  get_height()     { return _height; }
double  get_area()       { return _area; }
void    compute_height() { _height = _point_B->get_y() - _point_A->get_y();}
void    compute_area()   { _area = _height * get_width(); }
QString get_point_A()    { return _point_A->get_ID(); }
QString get_point_B()    { return _point_B->get_ID(); }

private:

    void init();

    double _height, _area;

    Point* _point_A;
    Point* _point_B;

};
```

- Besides **direct dependencies** of attributes, **indirect dependencies** are of special interest.
- The **sequence** in which the attributes are updated is vital.
- Due to the continuous change of source and target data by the users of the related applications, the **links** between the attributes **are not static**.
- In a distributed environment, it is unlikely that all objects are known at a central **location**.
- The **number** of attributes is **high**.

Conclusion

- Standards for exchanging data and remote method invocation are available
- On their own, these standards do not solve the problems of engineering in distributed environments
- The development of methods for distributed engineering in computer networks require mathematical rigour, i.e. application of graph theory